From Minimum Cuts to Submodular Systems (and back) Standing on the Shoulders of Giants

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In the Beginning...

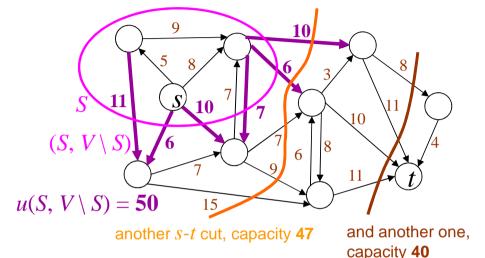
...worked under the mentorship of **Jean-Claude Picard** (1938-1999) on **minimum** (*s*,*t*)-cuts in networks – learning from some earlier giants:

- Maxflow Mincut Theorem [P. Elias, A. Feinstein, & C.E. Shannon, 1956; L.R. Ford, Jr. & D.R. Fulkerson, 1956]
- Minimum (*s*,*t*)-cuts as instances of pseudo-Boolean programming [P.L.Hammer (Ivanescu), 1965]
- Binary maximization of quadratic polynomials with nonnegative quadratic coefficients as minimum (s,t)-cuts problems [J.-C. Picard & H.D. Ratliff, 1975]
- Maximum weight closure of a graph (poset ideal or filter) as a minimum (*s*,*t*)-cut problem, and application to open pit mining [J.-C. Picard, 1976]

Minimum (s,t) cuts

In a directed graph G = (V, A) with

- a source s and a sink t in V ($s \neq t$) and
- arc capacities $u_{ij} \ge 0$ for all $ij \in A$ an (s,t)-cut $(S,V\setminus S)$ is the set of all arcs $ij \in A$ with $i \in S$ and $j \notin S$, with source set $S \subset V$ containing S and not S
- its capacity is $u(S, V \setminus S) = \sum_{ij \in (S, V \setminus S)} u_{ij}$



[P.L.Hammer (Ivanescu), 1965]: let binary variable $x_i = 1$ if $i \in S$, and 0 otherwise

$$u(S, V \setminus S) = \sum_{ij \in A} u_{ij} x_i (1 - x_j)$$

[J.-C. Picard & H.D. Ratliff, 1975]: conversely, every quadratic polynomial

$$f(x) = \frac{1}{2} x^{T} Q x + b^{T} x$$

in n binary variables with all non-diagonal quadratic coefficients $q_{ij} \ge 0$ $(i \ne j)$ may be maximized by solving a minimum (s,t)-cut problem

Minimum (s,t)-cuts

Joint work with **Jean-Claude Picard** on minimum (s,t)-cuts

- On the structure of all minimum cuts in a network and applications (1980): the lattice structure of minimum cuts
- A network flow solution to some nonlinear 0-1 programming problems, with applications to graph theory (1982): hyperbolic optimization problems and nested parametric minimum cuts
- Selected applications of minimum cuts in networks (1982), from the binary quadratic programming formulation and parametric properties
- Ranking the cuts and cut-sets of a network (with H. Hamacher, 1984)

Minimum (s,t)-cuts as instances of algebraic lattices

- The intersection $S \cap S'$ and the union $S \cup S'$ of two minimum (s,t)-cuts S and S' are also minimum (s,t)-cuts $[\emptyset]$. Ore, 1962
- An (algebraic) **lattice** is a poset (partially ordered set) in which every two elements x and y have a greatest common lower bound, their meet $x \wedge y$, and a smallest common upper bound, their join $x \vee y$
- Structure of sublattices of **product spaces** (products of chains, such as \mathbb{R}^n or \mathbb{Z}^n) [D.M. Topkis, 1976; A.M. (Pete) Veinott, Jr., 1989]

Joint work with Fabio Tardella on the structure of sublattices:

- Bimonotone linear inequalities and sublattices of \mathbb{R}^n (2006): characterize closed convex sublattices of \mathbb{R}^n
- Sublattices of product spaces: Hulls, representation and counting (2008): representations with proper boundary epigraphs allow counting sublattices of finite products of finite chains, and yield a good characterization and a polytime algorithm for sublattice hull membership
- Carathéodory, Helly and Radon numbers for sublattice convexities (t.a.): exact or approximate values of convexity invariants for several convexities defined by sublattices of \mathbf{B}^n , \mathbf{R}^n and \mathbf{Z}^n

(s,t)-cut functions are submodular

The cut (capacity) function $f: 2^V \to \mathbb{R}$, where $f(S) = u(S, V \setminus S)$ is the capacity of the (s,t)-cut defined by S, satisfies the **submodular inequality**

$$f(S \cap S') + f(S \cup S') \le f(S) + f(S')$$
 for all $S, S' \subset V$

Pioneering work of Jack Edmonds (1970) on submodular set functions, greedy algorithms and polymatroids (also L. Lovász, S. Fujishige, etc.)

• A general class of greedily solvable linear programs (with F. Spieksma & F. Tardella, 1998): duality relationship with transportation problems satisfying a Monge condition

Applications to sequencing and scheduling:

- Structure of a simple scheduling polyhedron (1993): Smith's rule (WSPT, c-μ rule) is an instance of the polymatroid greedy algorithm in disguise (see also [L. Wolsey, 1985])
- Single machine scheduling with release dates (with M. Goemans, A. Schulz, M.Skutella & Y. Wang, 2002)
- Approximation algorithms for shop scheduling problems with minsum objective (with M.Sviridenko, 2002)
- On the asymptotic optimality of a simple on-line algorithm for the stochastic single machine weighted completion time problem and its extensions (with C. Chou, H. Liu & D. Simchi-Levi, 2006)

Parametric minimum (s,t)-cuts

Let the arc capacities $u_{ij}(\lambda)$ be functions of a parameter λ Two key properties:

• Structural property: if the capacities of the source arcs (s,v) are increasing functions of λ and those of the sink arcs (v,t) decreasing functions of λ then minimum (s,t)-cuts $S(\lambda)$ are increasing (nested) [M.J. Eisner & D.G. Severance, 1976; H.S. Stone, 1978; Picard & Q. 1982]

an instance of parametric submodular optimization [D.M. Topkis, 1978]

• Algorithmic property: full parametric analysis in about the same time as a single minimum (*s*,*t*)-cut computation [G. Gallo, M.D. Grigoriadis & R.E.Tarjan, 1989, known as "GGT"]

Further extensions of structural and algorithmic properties:

• Monotone parametric min cut revisited: Structures and algorithms (with F.Granot, S.T. McCormick & F. Tardella, 2012)

Further applications of minimum (s,t)-cuts

• A study of the Bienstock-Zuckerberg algorithm: Applications in mining and resource constrained project scheduling (with G. Muñoz, D. Espinoza, M. Goycoolea, E. Moreno & O. Rivera, submitted)

The Maxflow-Mincut Thm is a special case of the Kantorovich Duality of (infinite dimensional) optimal transport problems:

- Optimal pits and optimal transportation (with I. Ekeland, 2015): a continuous space optimum closure model
- Combinatorial bootstrap inference in partially identified incomplete structural models (with M. Henry & R. Meango, 2015): an application to econometrics (extending work of I. Ekeland, A. Galichon & M. Henry)

Global minimum cuts and symmetric submodular functions

• There are simpler and faster algorithms for finding global minimum cuts in undirected networks than solving |V|-1 minimum (s,t)-cut problems [H.Nagamochi &T. Ibaraki, 1992; D.R. Karger, 1993; D.R. Karger & C.Stein, 1993]

Main thesis [Q 1999]: "most properties of global cuts are properties of symmetric submodular functions"

- i.e., submodular set functions such that $f(S) = f(V \setminus S)$ for all $S \subseteq V$
- Minimizing symmetric submodular functions (1998): a genuinely combinatorial $O(|V|^3)$ algorithm, extending the MA ordering approach of Nagamochi & Ibaraki
 - Renewed interest in seeking combinatorial (non-ellipsoid) algorithms for minimizing (general) submodular set functions [A. Schrijver [EURO Gold Medal 2015], 2000; S. Iwata, L. Fleischer & S. Fujishige, 2001; etc.]
 - Applied to statistical physics [J.-Ch. Anglès d'Auriac, F. Iglói, M. Preissmann & A. Sebö, 2002] and clustering [M. Narasimhan, N. Jojic & J. Bilmes, 2005]

Parametric global minimum cuts

• Parametric global minimum cuts lack the Structural and Algorithmic properties of parametric minimum (s,t)-cuts

However, whereas virtually every parametric combinatorial optimization problem has a super-polynomial number of (Pareto) efficient solutions (including minimum (s,t) cuts [P. Carstensen, 1983]), parametric global minimum cuts have a polynomial number of efficient solutions, and polytime algorithms for enumerating them; e.g., for a single parameter λ :

- About $O(|V|^{19})$ efficient solutions [K. Mulmuley, 1999]
- Strongly polynomial bounds for multiobjective and parametric global minimum cuts in graphs and hypergraphs (with H. Aissi, R. Mahjoub, S.T. McCormick, 2015): $O(|V|^7)$ efficient solutions
- Improved algorithms and insights [Karger, 2016]



Thank you for your interest and attention

...and my apologies to the many contributors I did not cite